

DATE: Wednesday, September 10, 2003 Printable Copy Create Case





DB=USPT,PGPB,JPAB,EPAB,DWPI,TDBD; PLUR=YES; OP=ADJ L24 L23 and l20 4 L2 L23 L22 near l21 15557 L2 L22 force 2002111 L2 L21 damp\$3 294328 L2 L20 L19 and l10 126 L2 L19 L18 or l14 4521 L1 L18 L17 or l15 or l16 2458 L1 L17 under near steer\$3 1290 L1 L16 under-steer\$3 362 L1 L15 understeer\$3 1250 L1	ame t set				
L23 L22 near l21 15557 L2 L22 force 2002111 L2 L21 damp\$3 294328 L2 L20 L19 and l10 126 L2 L19 L18 or l14 4521 L1 L18 L17 or l15 or l16 2458 L1 L17 under near steer\$3 1290 L1 L16 under-steer\$3 362 L1	DB= $USPT$, $PGPB$, $JPAB$, $EPAB$, $DWPI$, $TDBD$; $PLUR$ = YES ; OP = ADJ				
L22 force 2002111 L2 L21 damp\$3 294328 L2 L20 L19 and l10 126 L2 L19 L18 or l14 4521 L1 L18 L17 or l15 or l16 2458 L1 L17 under near steer\$3 1290 L1 L16 under-steer\$3 362 L1	<u>4</u>				
L21 damp\$3 294328 L2 L20 L19 and l10 126 L2 L19 L18 or l14 4521 L1 L18 L17 or l15 or l16 2458 L1 L17 under near steer\$3 1290 L1 L16 under-steer\$3 362 L1	<u>3</u>				
L20 L19 and l10 126 L2 L19 L18 or l14 4521 L1 L18 L17 or l15 or l16 2458 L1 L17 under near steer\$3 1290 L1 L16 under-steer\$3 362 L1	2				
L19 L18 or l14 4521 L1 L18 L17 or l15 or l16 2458 L1 L17 under near steer\$3 1290 L1 L16 under-steer\$3 362 L1	<u>1</u>				
L18 L17 or l15 or l16 2458 L1 L17 under near steer\$3 1290 L1 L16 under-steer\$3 362 L1	<u>0</u>				
$\begin{array}{cccc} \underline{L17} & \text{under near steer}\$3 & 1290 & \underline{L1} \\ \underline{L16} & \text{under-steer}\$3 & 362 & \underline{L1} \end{array}$	9				
<u>L16</u> under-steer\$3 362 <u>L1</u>	<u>8</u>				
	<u>7</u>				
<u>L15</u> understeer\$3 1250 <u>L1</u>	<u>6</u>				
	<u>5</u>				
<u>L14</u> L13 or 112 or 111 3131 <u>L1</u>	<u>4</u>				
<u>L13</u> oversteer\$3 1341 <u>L1</u>	<u>3</u>				
<u>L12</u> over-steer\$3 420 <u>L1</u>	<u>2</u>				
$\underline{L11}$ over near steer\$3 1907 $\underline{L1}$	<u>1</u>				
<u>L10</u> 18 and 15 and 19 203 <u>L1</u>	<u>0</u>				
$\underline{\text{L9}}$ steering angle 17436 $\underline{\text{L9}}$	<u>)</u>				
<u>L8</u> L7 near 16 65769 <u>L8</u>	<u> </u>				
$\underline{L7}$ speed or velocity 2317802 \underline{L}	7				
<u>L6</u> vehicle 1378510 <u>L6</u>	<u>5</u>				
<u>L5</u> L4 near4 l3 339 <u>L5</u>	<u> </u>				
<u>L4</u> compar\$3 1832161 <u>L4</u>	<u> </u>				
<u>L3</u> 11 near 12 4717 <u>L3</u>	<u> </u>				
<u>L2</u> rate 1835904 <u>L2</u>	<u> </u>				
<u>L1</u> yaW 18001 <u>L</u> 3					

END OF SEARCH HISTORY



T tal Assignments: 1

Application #: 10033870 Filing Dt: 12/28/2001 Patent #: NONE Issue Dt:

PCT #: NONE Publication #: 20030047994 Pub Dt: 03/13/200

Inventor: You-Seok Koh

Title: Method for controlling a damper of a vehicle

Assignment: 1

Reel/Frame: 012437/0615 Received: Recorded: Mailed: 03/04/2002 Pages:

Conveyance: ASSIGNMENT OF ASSIGNORS INTEREST (SEE DOCUMENT FOR DETAILS).

Assignor: KOH, YOU-SEOK Exec Dt: 12/24/2001

Assignee: MANDO CORPORATION

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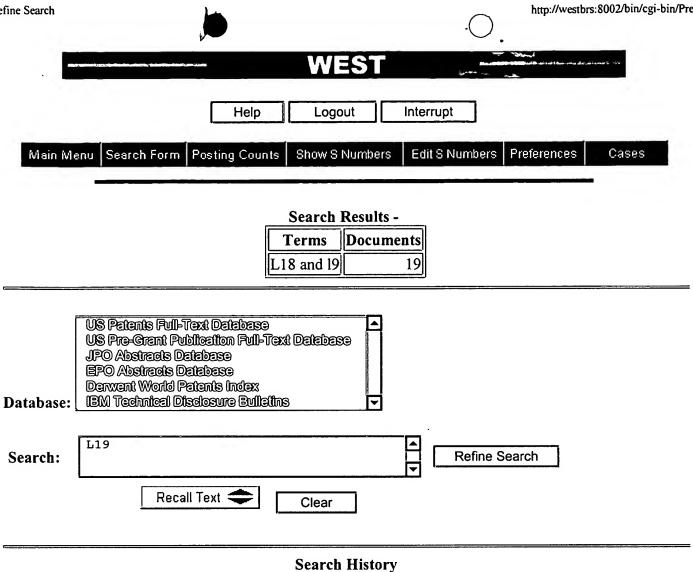
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Search Results as of: 9/10/2003 9:03:57 A.M.

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DATE: Tuesday, September 09, 2003 Printable Copy Create Case

Set Name side by side	Query	Hit Count	Set Name result set
DB = USPT, PGPB,	JPAB,EPAB,DWPI,TDBD; PLUR=YES; OP=ADJ		
<u>L19</u>	L18 and 19	19	<u>L19</u>
<u>L18</u>	L17 and 116	1068	<u>L18</u>
<u>L17</u>	114 or 113 or 110	3131	<u>L17</u>
<u>L16</u>	L15 or 112 or 111	2458	<u>L16</u>
<u>L15</u>	under-steer\$3	362	<u>L15</u>
<u>L14</u>	over-steer\$3	420	<u>L14</u>
<u>L13</u>	oversteer\$3	1341	<u>L13</u>
<u>L12</u>	understeer\$3	1250	<u>L12</u>
<u>L11</u>	under near steer\$3	1290	<u>L11</u>
<u>L10</u>	over near steer\$3	1907	<u>L10</u>
<u>L9</u>	L8 and 17 and 13 and 16	54	<u>L9</u>
<u>L8</u>	14 near3 15	92825	<u>L8</u>
<u>L7</u>	11 near3 12	4983	<u>L7</u>
<u>L6</u>	"damping force"	13050	<u>L6</u>
<u>L5</u>	velocity or speed	2317802	<u>L5</u>
<u>L4</u>	vehicle	1378510	<u>L4</u>
<u>L3</u>	"steering angle"	17436	<u>L3</u>
<u>L2</u>	rate	1835904	<u>L2</u>
<u>L1</u>	yaw	18001	<u>L1</u>

END OF SEARCH HISTORY